

METHOD FOR CORRECTING SPEED FEEDBACK IN A PERMANENT-MAGNET MOTOR

The present invention relates to a method as defined 5 in the preamble of claim 1 for correcting speed feedback in a synchronous permanent-magnet motor.

The problem is that, in prior art, speed feedback in a synchronous permanent-magnet motor changes slowly e.g. 10 as a function of temperature. When used as an elevator drive machine, the permanent-magnet motor is typically subjected to long-lasting peak-level loads, during which the temperature of the elevator machine rises. As the machine is developing heat, the speed feedback 15 sensor attached to the machine also becomes heated. In the present context, the above-mentioned speed feedback sensor is a tachometer. Thus, the speed information obtained from the tachometer changes as a function of the temperature of the machine and especially 20 of the tachometer. In the above-mentioned situation, the speed feedback information typically includes a 3-% gain and zero error, which is visible in the entire speed regulation system. A rise in the machine temperature may naturally also be due to development of 25 heat in the elevator shaft when a synchronous permanent-magnet motor is used as an elevator drive motor.

Previously known solutions attempted in order to deal with the above-mentioned problem include generating an 30 advance estimate of the speed signal error produced in the above-described manner and eliminating the error on an average. However, this method would not lead to accurate and reliable correction of the error.

35 Another known way of solving the aforesaid problem is based on measurement of speed feedback. In this case, a known distance is traversed at a known speed, so the speed feedback error can be corrected at the operating

point in question. The problem with this method is the continuously changing operating point, so the correction is naturally inaccurate.

5 The object of the invention is to eliminate the above-mentioned drawback in static correction of speed feedback.

10 A specific object of the invention is to disclose a method for continuous correction of speed feedback in a synchronous permanent-magnet motor that is better than prior-art methods.

15 In precise terms, the method of the invention for correcting speed feedback in a synchronous permanent-magnet motor is characterized by what is presented in the characterization part of claim 1. The features characteristic of certain other preferred embodiments of the invention are presented in the subclaims.

20 The method of the invention provides significant advantages as compared with prior art.

25 The method of the invention allows advantageous correction of non-linearities in the measurement of the speed of a synchronous permanent-magnet motor. A specific object of the invention is to correct the slow drift of speed feedback in the measurement of the speed of a synchronous permanent-magnet motor. This 30 aforesaid drift may occur e.g. in relation to temperature.

35 Another advantage of the method of the invention is that it is an adaptive method, which means that, once the initial values have been set, the method learns the correct factors. In addition, in the calculation of the parameters to be used in the method, it is possible to include a forgetting factor, which makes it

possible to perform the changing of the aforesaid parameters in a controlled manner. Via controlled changing of the above-mentioned parameters, it is possible to achieve some correction of the direction dependence 5 of the zero and gain error.

The present invention concerns a method for correcting speed feedback in a synchronous permanent-magnet motor. In the most preferred embodiment of the invention, the averages of speed reference and speed measurement for constant-speed downward travel are calculated. In a corresponding manner, the average of speed 10 reference and speed measurement for constant-speed upward travel is calculated. Next, the gain and zero factors to be used in the calculation are identified 15 and the measured speed measurement value is corrected to the correct value.

All the above-mentioned averages of speeds are calculated using the sum of the respective speeds and the 20 number of samples. For example, the average of the speeds of downward constant-speed travel is calculated by dividing the sum of the speeds of constant-speed downward travel by the number of samples of downward 25 constant speed. Similarly, the average of the speeds of constant-speed upward travel is calculated by dividing the sum of the speeds of constant-speed upward travel by the number of samples of upward constant speed.

30 In a preferred embodiment of the invention, the synchronous permanent-magnet motor of the method is used as an elevator drive machine.

35 According to the method, the speed gain factor and the speed zero factor are first assigned certain initial values. After this, new speed gain and zero factors are calculated.

According to the invention, the aforesaid speed gain factor and speed zero factor are updated by a forgetting factor. This aforesaid forgetting factor is an 5 exponential factor. This aforesaid forgetting factor is used in the present method so that, by applying the aforesaid forgetting factor, measurement samples of recent history are given more weight as compared with later measurement samples.

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In the foregoing, the invention has been described by way of example while different embodiments of the invention are possible within the scope of the inventive idea defined in the claims.